

include Directory Reference

Directory dependency graph for include:

/builds/airbot/shipping/build/src/airbot/sdk_server/client/C++/include

Files

[airbot_sdk.hpp](#)

Main SDK interface for controlling Airbot robotic arm.

[driver_state.hpp](#)

Defines operational states for the driver service.

[robot_mode.hpp](#)

Defines control modes for robot arm operations.

[speed_profile.hpp](#)

Defines speed profiles for robot motion control.